



# Anisotropic thermal lattice Boltzmann simulation of 2D natural convection in a square cavity



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## ABSTRACT

Natural convection in a square cavity is simulated by multiple relaxation time (MRT) lattice Boltzmann method (LBM) with a separate distribution function to solve for the temperature distribution. The Rayleigh numbers examined range from  $Ra = 10^3$  to  $Ra = 10^6$ . The simulations are performed for anisotropic thermal case and compared to isotropic thermal case.

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## 1. Introduction

Lattice Boltzmann method (LBM) [2,26,37,39] has been successfully applied to various hydrodynamic problems and the major advantage of the LBM is explicit formulation. However, its application to non-isothermal problem is limited because of the numerical instability for thermal models [32]. In general, there are three thermal lattice Boltzmann methods (TLBM) named the multi speed approach [1], the passive scalar approach and the double population approach.

The multi-speed approach adopts a single distribution function in order to obtain the macroscopic dynamic and thermal equations [1]. However, the Prandtl number is fixed and this approach suffers from lack of numerical stabilities.

The passive scalar approach also called hybrid method, consists of solving velocity field using LBM and the macroscopic temperature is solved by different numerical methods (e.g. finite difference or finite volume) [24,30]. This approach is more stable than the multi speed approach. But it has two disadvantages: first the viscous heat dissipation and compression work done by pressure cannot be incorporated, and second the simplicity of LBM is lost.

The double population method, is first used by He et al. [19]. This approach can be regarded as another version of the passive scalar method. In fact to solve macroscopic temperature another LBM distribution is used. This model has a better numerical stability than the multi speed approach, and the viscous heat dissipation and compression work done by the pressure can be solved implicitly. Peng et al. [35] proposed a simplified thermal energy distribution model where the compression work done by the pressure and the viscous heat dissipation are neglected. By introducing a forcing function, Guo et al. [17] proposed a thermal lattice BGK equation with viscous heat dissipation in the incompressible limit.

The thermally driven cavity with adiabatic top and bottom walls (also called natural convection in a square cavity) is a classical benchmark to examine the accuracy of the scheme. The solution is given for 4 values of the Rayleigh number ( $Ra$ ), ( $Ra = 10^3, 10^4, 10^5$  and  $10^6$ ). The value of the Prandtl number ( $Pr$ ) is equal to 0.71, which corresponds to a cavity filled by air. The reference solution of this problem is given by De Vahl Davis [4].

To validate double population LBM method few researchers [10,16,18,21,29] have carried out the above problem. We note here that most of this works are using simple relaxation time (SRT), also called Lattice Boltzmann Bhatnagar–Gross–Krook (LBGK). This is due to extreme simplicity of this method. Even that LBGK suffers from lack of numerical stability and inaccuracy in implementing boundary conditions.

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In this paper we present a double population approach using multiple relaxation time lattice Boltzmann method (MRT-LBM) [38] with D2Q9 lattice model for solving velocity field and another D2Q9 for solving macroscopic temperature. The choice of D2Q9 model for thermal is to be able to model anisotropic thermal diffusion. We note that anisotropic thermal diffusion have many applications in diffusivity study of gas diffusion layer (see [34] for measurements and [11] for computations), advection and anisotropic-dispersion equation, porous media (see e. g. [7,13,15]).

First we consider natural convection in a square cavity when the flow is laminar (i.e. Rayleigh number is less than  $10^6$ ). To validate our model, we choose isotropic thermal diffusivity (i.e. diffusivity in  $x$  direction  $\kappa_x$  is equal to diffusivity in  $y$  direction  $\kappa_y$ ). Then we consider anisotropic thermal diffusion. In fact we consider two cases  $\kappa_x = \kappa_y/2$  and  $\kappa_x = 2\kappa_y$ , and we compare the solution to the isotropic one.

This paper is organized as follows. In Section 2, a brief overview of the MRT D2Q9 for advection-diffusion and the MRT D2Q9 for fluid problem. After in Section 3 we introduce the thermal LBM for the simulation of a Boussinesq fluid in a square cavity. In Section 4, results are presented and discussed. Finally, in Section 5 we conclude.

## 2. Multi relaxation time lattice Boltzmann method

### 2.1. Dynamic field

The multi relaxation time (MRT) lattice Boltzmann method [23] can be expressed as:

$$m_i^*(\vec{x}, t) = m_i(\vec{x}, t) - S_{ij}[m_j(\vec{x}, t) - m_j^{eq}(\vec{x}, t)] \quad (1)$$

$$f_i(\vec{x} + \vec{e}_i \Delta t, t + \Delta t) = M_{ij}^{-1} m_j^*(\vec{x}, t) \quad (2)$$

$m_i^*$ , Eq. (1), is the collision at the moment space and Eq. (2) represents the streaming operation. Here,  $\mathbf{M}$  is a matrix that transforms the distribution function  $\mathbf{f}$  to the velocity moment,  $\mathbf{m} = \mathbf{M}\mathbf{f}$ , and  $\mathbf{S}$  is the relaxation matrix. These will be defined later.

Based on the particle distribution functions, the macroscopic density and velocity are defined as:

$$\sum_i f_i = \rho, \quad \sum_i f_i \vec{e}_i = \rho \vec{u}. \quad (3)$$

For the present 2D applications, D2Q9 model are adopted to model fluid problems and the particle speed  $\vec{e}_i$  are defined as,

$$\begin{cases} \vec{e}_0 = 0, \\ \vec{e}_i = (\cos[\pi(i-1)/2], \sin[\pi(i-1)/2])c, \\ \text{for } i = 1, 2, 3, 4, \\ \vec{e}_i = (\cos[\pi(i-4-1/2)/2], \sin[\pi(i-4-1/2)/2])\sqrt{2}c, \\ \text{for } i = 5, 6, 7, 8, \end{cases}$$

where  $c = dx/dt$  is the lattice speed, and  $dx$  and  $dt$  are the lattice width and time step, respectively. Here,  $dt$  is chosen to be equal to  $dx$ , thus  $c = 1$ . Moreover, the speed of sound is  $C_s = c/\sqrt{3}$ .

The transformation matrix  $\mathbf{M}$  and the velocity moment vector  $\mathbf{m}$  are defined as,

$$\underbrace{\begin{bmatrix} m_0(\rho) \\ m_1(e) \\ m_2(\varepsilon) \\ m_3(j_x) \\ m_4(q_x) \\ m_5(j_y) \\ m_6(q_y) \\ m_7(p_{xx}) \\ m_8(p_{xy}) \end{bmatrix}}_{\mathbf{m}} = \underbrace{\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ -4 & -1 & -1 & -1 & -1 & 2 & 2 & 2 & 2 \\ 4 & -2 & -2 & -2 & -2 & 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & -1 & 0 & 1 & -1 & -1 & 1 \\ 0 & -2 & 0 & 2 & 0 & 1 & -1 & -1 & 1 \\ 0 & 0 & 1 & 0 & -1 & 1 & 1 & -1 & -1 \\ 0 & 0 & -2 & 0 & 2 & 1 & 1 & -1 & -1 \\ 0 & 1 & -1 & 1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & -1 & 1 & -1 \end{bmatrix}}_{\mathbf{M}} \underbrace{\begin{bmatrix} f_0 \\ f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ f_6 \\ f_7 \\ f_8 \end{bmatrix}}_{\mathbf{f}} \quad (4)$$

and the equilibria of the velocity moments  $\mathbf{m}^{eq}$  are,

$$\begin{cases} \rho^{eq} = \rho, & e^{eq} = -2\rho + \frac{3}{\rho}(j_x^2 + j_y^2), & \varepsilon^{eq} = \rho - \frac{3}{\rho}(j_x^2 + j_y^2), \\ j_x^{eq} = j_x, & q_x^{eq} = -j_x, & j_y^{eq} = j_y, & q_y^{eq} = -j_y, \\ p_{xx}^{eq} = \frac{1}{\rho}(j_x^2 - j_y^2), & p_{xy}^{eq} = \frac{j_x j_y}{\rho}. \end{cases} \quad (5)$$

The relaxation matrix  $\mathbf{S}$  is a diagonal matrix, i.e.,

$$\mathbf{S} = \text{diag}[s_0, s_1, s_2, s_3, s_4, s_5, s_6, s_7, s_8] \quad (6)$$

where  $s_0 = s_3 = s_5 = 0$  enforces mass and momentum conservation before and after collision [23]. Here,  $s_4 = s_6 \equiv s_q$ ,  $s_7 = s_8 \equiv s_v$ , thus the viscosity formulation is the same as that by the SRT model as shown in [23], i.e. the corresponding kinematic viscosity is  $\nu = (\frac{1}{s_v} - \frac{1}{2})C_s^2 dt$  in the simulation. More specifically, we choose to use the following relationship between two relaxation rates:  $s_q = 8 \frac{(2-s_v)}{(8-s_v)}$  where  $s_q \equiv s_4 = s_6$ . See [8,14] for more details.

We note that, the MRT model can recover to SRT model if  $s_1 = s_2 = s_4 = s_6 = s_7 = s_8 = s_v$ .

### 2.2. Thermal field

The thermal field is modeled using the passive scalar approach to enhance the numerical stability, where a separate distribution function is used to solve for the temperature distribution [27,35,36]. The D2Q9 model introduced in the above section is adopted. The evolution of the scalar MRT LB scheme is given as:

$$\tilde{m}_i^*(\vec{x}, t) = \tilde{m}_i(\vec{x}, t) - \sigma_{ij}[\tilde{m}_j(\vec{x}, t) - \tilde{m}_j^{eq}(\vec{x}, t)] \quad (7)$$

$$g_i(\vec{x} + \vec{e}_i \Delta t, t + \Delta t) = M_{ij}^{-1} \tilde{m}_j^*(\vec{x}, t) \quad (8)$$

Here,  $f_i$  is replaced by  $g_i$  in Eq. (2), because  $g_i$  is now the energy distribution function. The transformation matrix is the same as in equation (4), thus  $\tilde{\mathbf{m}} = \mathbf{M}\mathbf{g}$ . Again,  $\tilde{m}_i^*$  is the scalar collision at the moment space.  $\sigma$  is the diagonal relaxation matrix, i.e.

$$\sigma = \text{diag}[\sigma_0, \sigma_1, \sigma_2, \sigma_3, \sigma_4, \sigma_5, \sigma_6, \sigma_7, \sigma_8] \quad (9)$$

where  $\sigma_0 = 0$  enforces energy conservation,  $\tilde{m}_0 = \sum_i g_i = T$ , before and after collision.

The equilibrium values  $\tilde{m}_i^{eq}$  of the nonconserved moments are given by (see [22] for more details):

$$\begin{aligned} \tilde{m}_1^{eq} &= \tilde{\alpha}T + 3T(u^2 + v^2), \\ \tilde{m}_2^{eq} &= \tilde{\beta}T, \\ \tilde{m}_3^{eq} &= uT, \\ \tilde{m}_4^{eq} &= uT(-1 + 3(u^2 + v^2)), \\ \tilde{m}_5^{eq} &= vT, \\ \tilde{m}_6^{eq} &= vT(-1 + 3(u^2 + v^2)) \\ \tilde{m}_7^{eq} &= a_x T + T(u^2 - v^2), \\ \tilde{m}_8^{eq} &= a_y T + T(uv), \end{aligned}$$

where  $\mathbf{V} \equiv (u, v)$  is the dynamic field.

Using Taylor expansion [5,6] or Chapman–Enskog procedure [12], the advection diffusion [15] equation with an-isotropic coefficient up to order two in  $\Delta t$  can be expressed as:

$$\begin{aligned} \frac{\partial T}{\partial t} + U \frac{\partial T}{\partial x} + V \frac{\partial T}{\partial y} &= \frac{C_s^2 dt}{2} \left( \frac{1}{2} - \frac{1}{\sigma_3} \right) (\tilde{\alpha} + 3a_x + 4) \frac{\partial^2 T}{\partial x^2} \\ &+ \frac{C_s^2 dt}{2} \left( \frac{1}{2} - \frac{1}{\sigma_5} \right) (\tilde{\alpha} + 3a_x + 4) \frac{\partial^2 T}{\partial y^2} \\ &+ \frac{3C_s^2 dt}{2} a_y \left( \frac{1}{\sigma_3} + \frac{1}{\sigma_5} - 1 \right) \frac{\partial^2 T}{\partial xy}, \end{aligned}$$

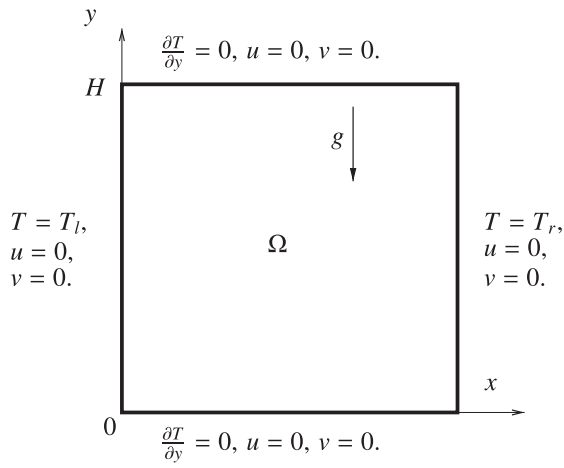


Fig. 1. Configuration of natural convection in a square cavity.

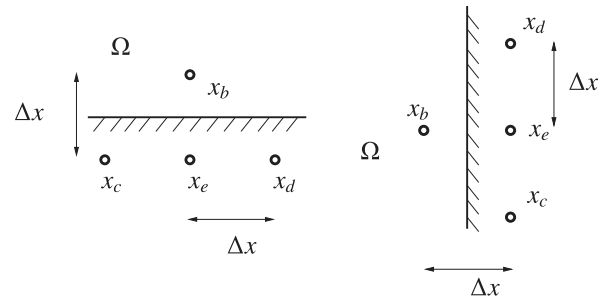


Fig. 2. Left: Boundary node  $x_b$  in the bottom of the domain  $\Omega$ . Right: Boundary node  $x_b$  in the right of the domain  $\Omega$ .

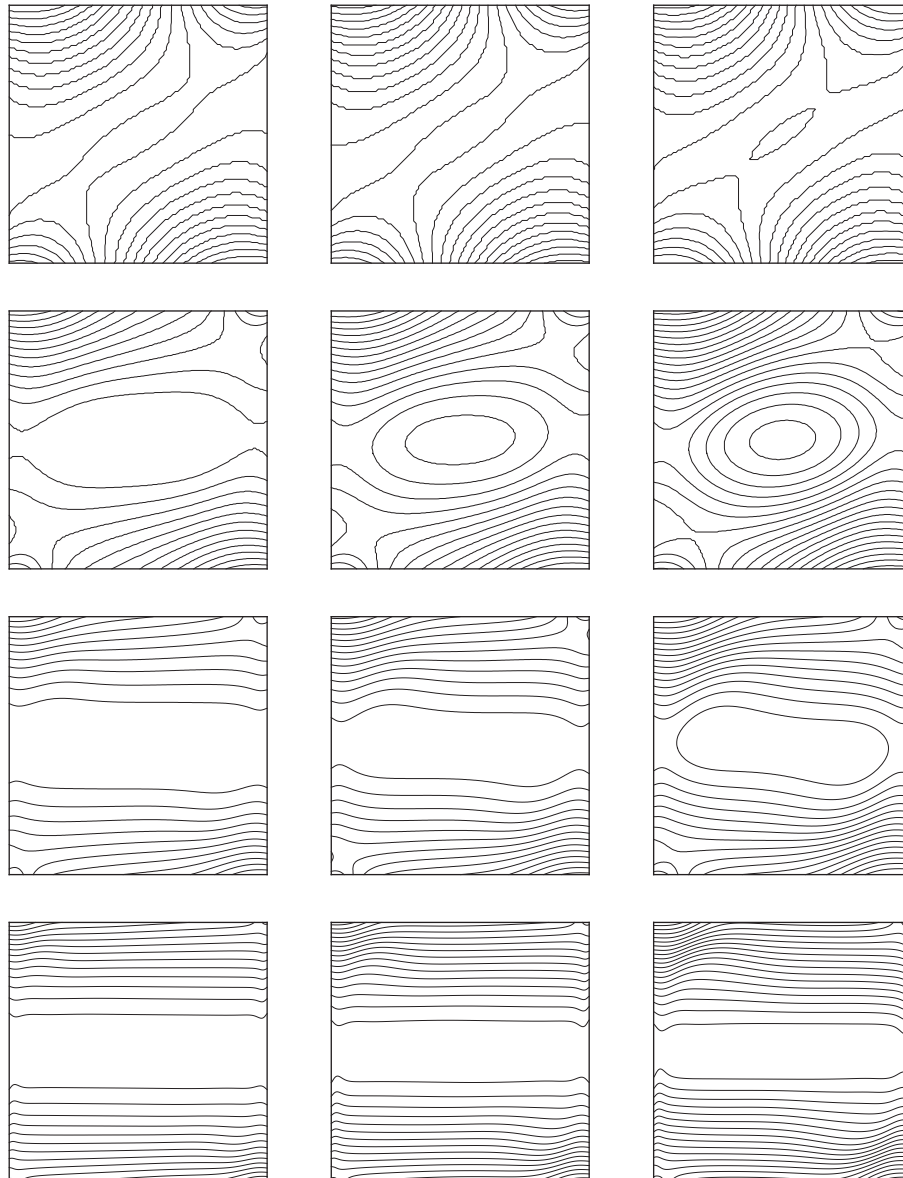
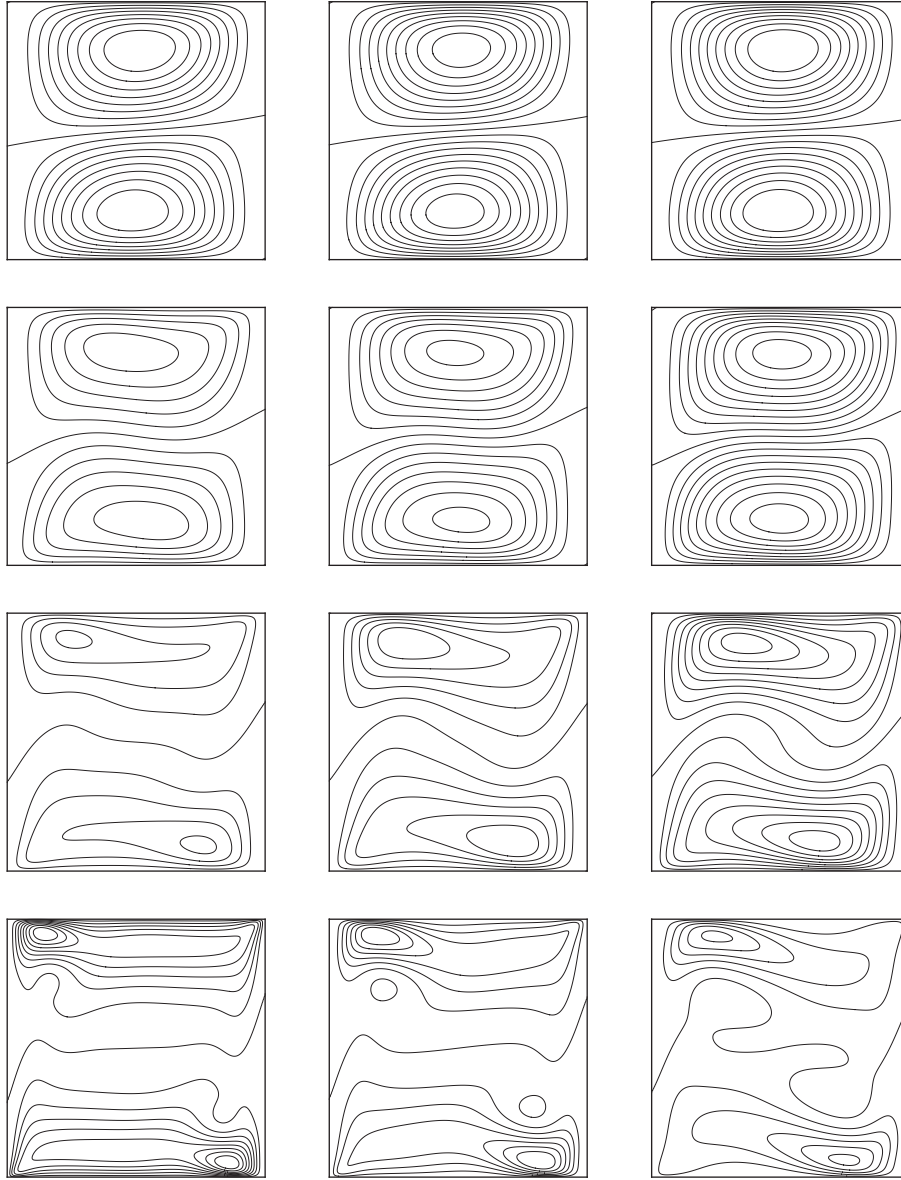


Fig. 3. Isobars ( $P$ ) of flow fields for  $Pr=0.71$ . From top to bottom  $Ra = 10^3, 10^4, 10^5$ , and  $10^6$  respectively for mesh size  $105^2, 155^2, 205^2$  and  $255^2$ . From left to right : (left)  $\kappa_x = \kappa_y/2$ , (center) isotropic case  $\kappa_x = \kappa_y$ , (right)  $\kappa_x = 2\kappa_y$ .





**Fig. 4.** First component of velocity ( $U$ ) of flow for  $Pr=0.71$ . From top to bottom  $Ra = 10^3, 10^4, 10^5$ , and  $10^6$  respectively for mesh size  $105^2, 155^2, 205^2$  and  $255^2$ . From left to right : (left)  $\kappa_x = \kappa_y/2$ , (center) isotropic case  $\kappa_x = \kappa_y$ , (right)  $\kappa_x = 2\kappa_y$ .

- The  $y$  direction momentum ( $j_y$ ) and energy flux ( $q_y$ ) are modified by adding half of the external force  $F_y$ , i.e.

$$\bar{j}_y = j_y + \frac{\Delta t}{2} F_y, \quad \bar{q}_y = q_y - \frac{\Delta t}{2} F_y,$$

- Compute the equilibrium moments in Eq. (5) using  $\bar{j}_y$  and  $\bar{q}_y$  to replace  $j_y$  and  $q_y$ .
- Perform collision in Eq. (1).
- Post collision  $y$  direction momentum and energy flux are modified by adding another half of the external force, i.e.,

$$\bar{j}_y^* = j_y^* + \frac{\Delta t}{2} F_y, \quad \bar{q}_y^* = q_y^* - \frac{\Delta t}{2} F_y,$$

- Perform streaming in Eq. (2) using  $\bar{j}_y^*$  and  $\bar{q}_y^*$  to replace  $j_y^*$  and  $q_y^*$ .

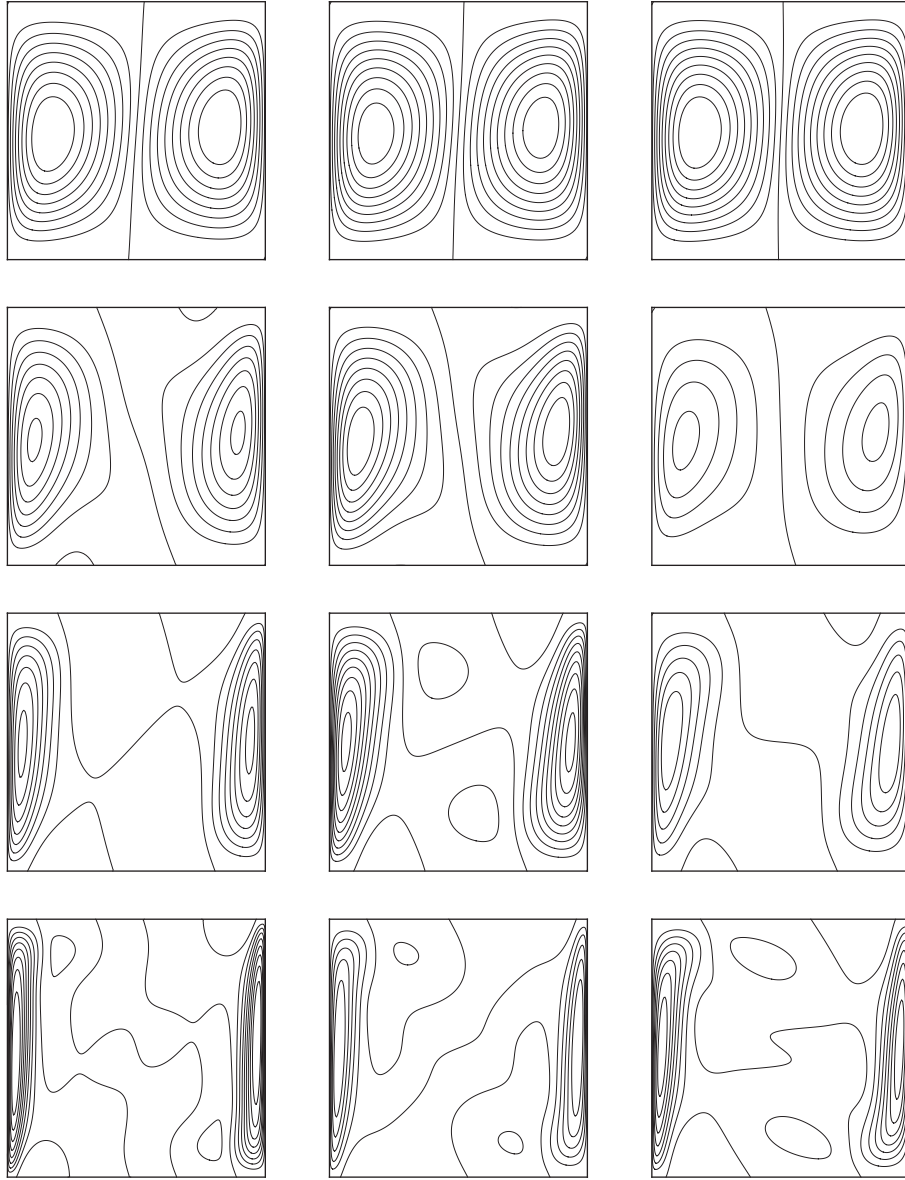
Other forms of forcing term accounted for the discrete effect could also be adopted [17]. It is noted that the compressibility may influence the results, and this can be eliminated by incompressible model

[20]. However, since the present Mach number is low, therefore this influence could be neglected [35].

#### 2.4. Geometry and boundary conditions

Natural convection in a square cavity  $\Omega = ]0, H[ \times ]0, H[$  (see Fig. 1) is considered, where the flow is bounded by a stationary square enclosure with sidewalls maintained at different temperatures and driven by the buoyancy force. For laminar convection in this flow configuration, the viscous heat dissipation is assumed to be negligible. The temperature difference between the walls introduces a temperature gradient in the fluid, and the consequent density difference induces a convective fluid motion. The left wall is at the higher uniform temperature  $T_l$  and the right wall is at the lower uniform temperature  $T_r$ . Both the top and bottom walls are adiabatic, i.e.  $\partial T / \partial y = 0$ . The summary of the boundary conditions is shown below.

$$u = v = 0 \text{ on } \partial\Omega \quad (13)$$



**Fig. 5.** Second component of velocity ( $V$ ) of flow for  $Pr=0.71$ . From top to bottom  $Ra = 10^3, 10^4, 10^5,$  and  $10^6$  respectively for mesh size  $105^2, 155^2, 205^2$  and  $255^2$ . From left to right: (left)  $\kappa_x = \kappa_y/2$ , (center) isotropic case  $\kappa_x = \kappa_y$ , (right)  $\kappa_x = 2\kappa_y$ .

$$T = T_l \text{ on } \{0\} \times [0, H] \tag{14}$$

$$T = T_r \text{ on } \{H\} \times [0, H] \tag{15}$$

$$\frac{\partial T}{\partial y} = 0 \text{ on } [0, H] \times \{0\} \text{ and } [0, H] \times \{H\} \tag{16}$$

For Dirichlet boundary condition for the velocity (13) at the walls of the cavity, the classical half way bounce-back boundary condition is adopted. So, for example, consider the bottom wall for a boundary node  $x_b$  (see left figure of Fig. 2), the following bounce-back boundary condition is applied.

$$\begin{aligned} f_2(x_b, t + \Delta t) &= f_4(x_e, t + \Delta t) = f_4^*(x_b, t), \\ f_5(x_b, t + \Delta t) &= f_7(x_c, t + \Delta t) = f_7^*(x_b, t), \\ f_6(x_b, t + \Delta t) &= f_8(x_d, t + \Delta t) = f_8^*(x_b, t). \end{aligned}$$

For the thermal boundary condition, the Dirichlet boundary conditions given by Eqs. (15) and (14) on the left and right wall of the domain  $\Omega$  are introduced. For a given constant temperature  $T$ , this

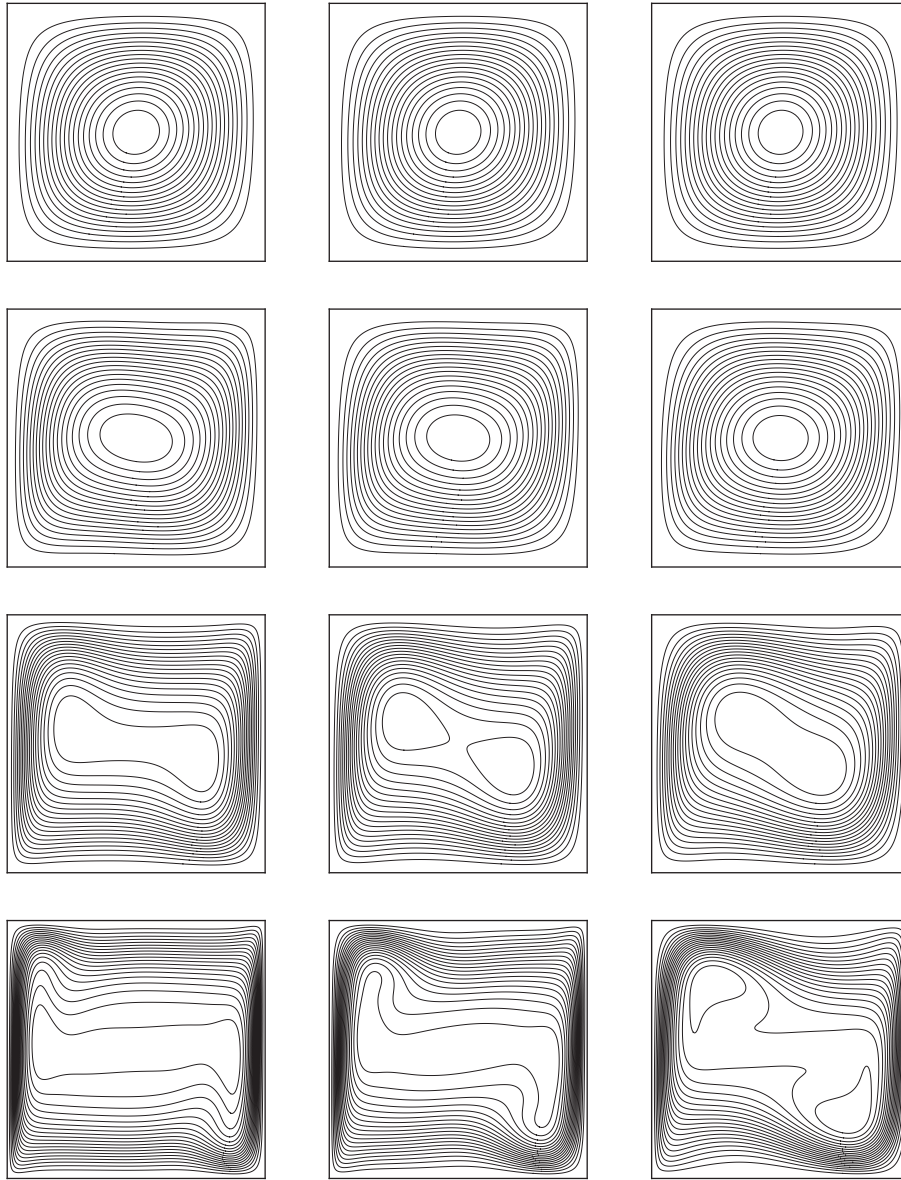
can be archived using the following scheme in boundary node  $x_b$  on the right wall (see right figure of Fig. 2) :

$$\begin{aligned} g_3(x_b, t + \Delta t) &= -g_1(x_e, t + \Delta t) + \frac{1}{36}(4 - \tilde{\alpha} - 2\tilde{\beta})T, \\ g_7(x_b, t + \Delta t) &= -g_5(x_c, t + \Delta t) + \frac{1}{36}(4 + 2\tilde{\alpha} + \tilde{\beta})T, \\ g_6(x_b, t + \Delta t) &= -g_8(x_d, t + \Delta t) + \frac{1}{36}(4 + 2\tilde{\alpha} + \tilde{\beta})T, \end{aligned}$$

For the Neumann boundary condition on the top and bottom wall of the domain  $\Omega$  given by Eq. (16), the classical “bounce back” scheme is adopted. Consider a boundary node  $x_b$  in the bottom wall (see right figure of Fig. 2), the following scheme is used.

$$\begin{aligned} g_2(x_b, t + \Delta t) &= g_4(x_e, t + \Delta t) = g_4^*(x_b, t), \\ g_5(x_b, t + \Delta t) &= g_7(x_c, t + \Delta t) = g_7^*(x_b, t), \\ g_6(x_b, t + \Delta t) &= g_8(x_d, t + \Delta t) = g_8^*(x_b, t). \end{aligned}$$

For more detail about how to reconstruct the above boundary condition for thermal problem see [7].



**Fig. 6.** Streamlines of flow fields ( $\Psi$ ) for  $Pr=0.71$ . From top to bottom  $Ra = 10^3, 10^4, 10^5$ , and  $10^6$  respectively for mesh size  $105^2, 155^2, 205^2$  and  $255^2$ . From left to right : (left)  $\kappa_x = \kappa_y/2$ , (center) isotropic case  $\kappa_x = \kappa_y$ , (right)  $\kappa_x = 2\kappa_y$ .

In the present parallel implementation, the single program multiple data (SPMD) environment is employed. Message-Passing-Interface (MPI) is adopted for the communication between the processors. The domain decomposition is done on direction of the computational domain, where the ghost cells are adopted along the inter-processor boundary.

### 3. Numerical results and discussion

#### 3.1. Isotropic case

Let consider the isotropic thermal case, *i. e.* the  $x$ - thermal diffusivity  $\kappa_x$  is equal to  $y$ - thermal diffusivity  $\kappa_y$  equal to a given thermal diffusivity  $\kappa$ . In this case we fix  $\sigma_3 = \sigma_5$  to have  $\kappa_x = \kappa_y$ , described by Eq. (11), equal to the given thermal diffusivity  $\kappa$ . For the present natural convection within the square cavity as shown in Fig. 1, the major control parameter is the Rayleigh number  $Ra = \beta g \Delta T H^3 Pr / \nu^2$  associated with the heat transfer within the fluid, where  $H$  is the height or width of the cavity.

The Nusselt number is also an important dimensionless parameter in describing the convective heat transport. Its average in the whole flow domain is defined as,

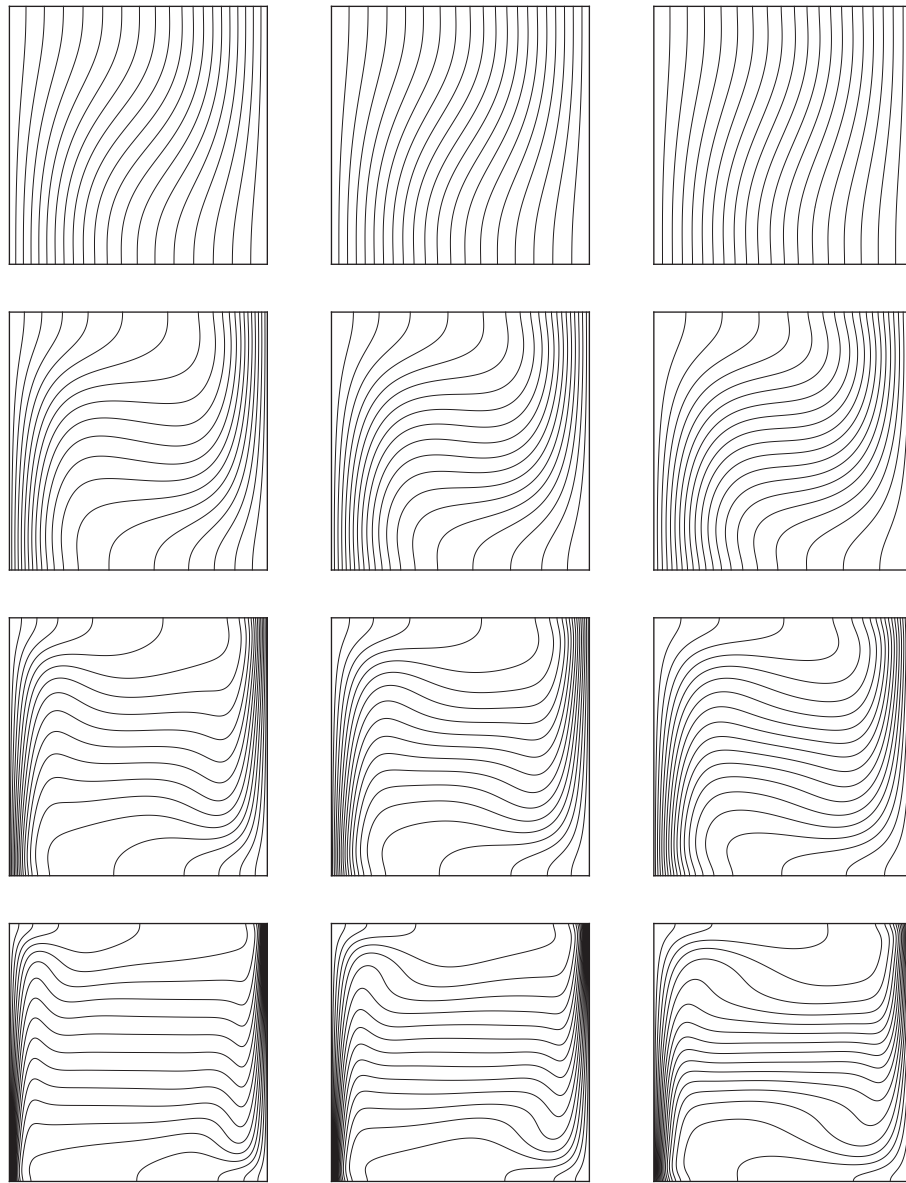
$$\overline{Nu} = \frac{1}{\kappa \Delta T} \int_0^H q_x(x, y) dy \quad (17)$$

where  $q_x(x, y) = uT(x, y) - \kappa \partial T(x, y) / \partial x$  is the local heat flux in the horizontal direction.

To compare with previous results, the main quantities to compute are :  $u_{max}$ ,  $y_{max}$ ,  $v_{max}$ ,  $x_{max}$  and  $\overline{Nu}$ . Where  $u_{max}$  and its location  $y_{max}$ , the maximum vertical velocity on the horizontal mid-plane of the cavity,  $v_{max}$  and its location  $x_{max}$ , the maximum horizontal velocity on the vertical mid-plane of the cavity and the average Nusselt number  $\overline{Nu}$ .

We compute, for some cases, the maximum stream function  $\psi_{max}$  on the whole domain. Where the stream function is determined from:

$$\nabla \cdot (\nabla \times \psi) = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y}.$$



**Fig. 7.** Isotherms of flow fields ( $T$ ) for  $Pr=0.71$ . From top to bottom  $Ra = 10^3, 10^4, 10^5$ , and  $10^6$  respectively for mesh size  $105^2, 155^2, 205^2$  and  $255^2$ . From left to right : (left)  $\kappa_x = \kappa_y/2$ , (center) isotropic case  $\kappa_x = \kappa_y$ , (right)  $\kappa_x = 2\kappa_y$ .

Note here that for the computation of  $\overline{Nu}$  described by Eq. (17), the temperature gradient  $\frac{\partial T}{\partial x}$  is needed. To calculate this gradient we do not do any additional interpolation method. In fact this quantity can be evaluated by using Taylor expansion [8] up to second-order of the non-conserved moment  $\tilde{m}_1$ :

$$\tilde{m}_1 = -\lambda^2 \Delta t \frac{1}{\sigma_\kappa} \left[ \frac{4 + \tilde{\alpha}}{6} \frac{\partial T}{\partial x} \right] + O(\Delta t^2).$$

All the velocities are normalized using the diffusion velocity  $\kappa/H$ . The temperature are dimensionless, locations  $x$  and  $y$  are normalized using  $H$ .

### 3.2. Stability and admissible grid

Let define the Mach number as follows:

$$Ma = \frac{U}{C_s}, \tag{18}$$

where the quantity  $U = \sqrt{\alpha g \Delta T H} = \sqrt{\frac{Ra}{Pr}} \frac{\nu}{H}$  is the characteristic velocity in thermal convective flows. So, to keep stability of the LBM scheme related dynamic field, the Mach number should be smaller than critical value  $\frac{3}{10}$  (see [38] for more details). As in numerical simulation the parameters are fixed as  $Pr = 0.71$  and  $\nu = 0.01$ , Eq. (18) gives a constrain on mesh size  $H$ . In fact, the mesh size must verify

$$\frac{10}{3} \frac{\nu}{C_s} \sqrt{\frac{Ra}{Pr}} < H. \tag{19}$$

Example for  $Ra = 10^7$  and  $Ra = 10^8$  the mesh size must satisfy  $H > 216$  and  $H > 685$ , respectively.

### 3.3. Grid dependence

We begin by the study of the grid dependence and the accuracy of the scheme. In fact, Table 1 gives the results for the simulation for Rayleigh number  $Ra = 10^6$  by using some different mesh sizes. We note that the calculated values approach the values given by the



benchmark of de Vahl Davis [4] and the benchmark of Le Quéré [25]. In other hand table shows also second order accuracy for every measured quantities. Where the accuracy is calculated by least squares method using relative error between the solution obtained by mesh size  $N^2$  and the reference one obtained by fine mesh ( $N_{ref}^2 = 1001^2$ ).

We have also see the grid dependance in the case of  $Ra = 10^8$  for the following mesh size :  $495 \times 495$ ,  $987 \times 987$  and  $2016 \times 2016$ . The Table 2 shows that the quantities calculated quickly approach the values given by the benchmark of the Le Quéré [25]. We note here that the first grid size do not resolve the stability condition Eq. (19). But this size still gives a good solution.

### 3.4. Isotropic test case

Many papers study the square heated cavity, for the following 4 values of the  $Ra$  numbers :  $Ra = 10^3$ ,  $10^4$ ,  $10^5$  and  $10^6$ . So we compare our results to the following results: de Vahl Davis [4] benchmark solution where second order finite differences scheme and a Richardson extrapolation scheme are used, Mayne et al. [31] using h-adaptive finite element method, Kuznik et al. [21] and Liu et al. [28] using TLBM based on the BGK and Mezrhab et al. [33] and Wang et al. [38] using TLBM based on MRT D2Q9 for flow and MRT D2Q5 for temperature.

Table 3 shows the numerical results where the domain is covered by a lattice sizes of  $105 \times 105$ ,  $155 \times 155$ ,  $205 \times 205$  and  $255 \times 255$ , respectively for  $Ra = 10^3$ ,  $10^4$ ,  $10^5$  and  $10^6$  compared to the results obtained by the methods listed above. The simulated results are contrasted with the benchmark solutions of De Vahl Davis [4] and the agreements are satisfactory. It is also noted that differences of the predicted velocities and average Nusselt number are less than 0.1%. The middle column of Figs. 3–7 show the solution predicted by the present double D2Q9 MRT LBE method for Rayleigh numbers  $Ra = 10^3$ , for  $Ra = 10^4$ ,  $Ra = 10^5$  and  $Ra = 10^6$  for isotropic case.

### 3.5. Anisotropic test case

In this section the effect of the anisotropy is performed. Let  $\kappa_x$  the  $x$  thermal diffusivity and  $\kappa_y$  the  $y$  thermal diffusivity. So we define the  $x$  Rayleigh number  $Ra_x = \beta g \Delta T H^3 \kappa_x / \nu$  associated with the  $x$  thermal diffusivity and  $Ra_y = \beta g \Delta T H^3 \kappa_y / \nu$  associated with the  $y$  thermal diffusivity. The choice of the anisotropy will be for different Rayleigh numbers fixed  $Ra_y = 10^3, \dots, 10^6$  as follows:

- $x$  thermal diffusivity given by  $\kappa_x = \frac{\kappa_y}{2}$ .
- $x$  thermal diffusivity given by  $\kappa_x = 2 \kappa_y$ .

The average of Nusselt number in the whole flow domain is defined now as,

$$\overline{Nu} = \frac{1}{\kappa_x \Delta T} \int_0^H q_x(x, y) dy \quad (20)$$

where  $q_x(x, y) = uT(x, y) - \kappa_x \partial T(x, y) / \partial x$  is the local heat flux in the horizontal direction.

To compare with isotropic results, the same main quantities to compute are :  $u_{max}$ ,  $y$ ,  $v_{max}$ ,  $x$  and  $\overline{Nu}$ . We remark that all the velocities are normalized using the  $y$  diffusion velocity  $\kappa_y / H$ .

First we study the convergence and the accuracy of the scheme for anisotropic case. In fact, Tables 4 and 5 give the results for the simulation in case of Rayleigh number  $Ra_y = 10^6$ , for  $\kappa_x = \frac{\kappa_y}{2}$  and  $\kappa_x = 2\kappa_y$ , respectively, by using some different mesh sizes. Tables 4 and 5 show also second order accuracy for every measured quantities. Here the accuracy is calculated by least squares method using relative error between the solution obtained by mesh size  $N^2$  and the reference one obtained by fine mesh ( $N_{ref}^2 = 1001^2$ ).

Table 6 shows the numerical results for three different cases:  $\kappa_x = \frac{\kappa_y}{2}$ ,  $\kappa_x = \kappa_y$  (isotropic case) and  $\kappa_x = 2\kappa_y$ . The domain is covered by a lattice sizes of  $105 \times 105$ ,  $155 \times 155$ ,  $205 \times 205$  and  $255$

$\times 255$ , respectively for  $Ra_y = 10^3$ ,  $10^4$ ,  $10^5$  and  $10^6$ . We note here that the  $u_{max}$  and  $v_{max}$  increase when the  $\kappa_x$  increase. This is due to the fact of the imposed hot wall (at  $x = 0$ ) and cold wall (at  $x = 1$ ) is in  $x$  direction.

Figs. 3–7 show the solution predicted by the present double D2Q9 MRT LBE method for Rayleigh numbers  $Ra_y = 10^3$ ,  $10^4$ ,  $10^5$  and  $10^6$  for anisotropic case. We refind here that the effect of  $x$  thermal diffusivity  $\kappa_x$  is more important than  $y$  thermal diffusivity  $\kappa_y$ . In fact when  $\kappa_x = 2\kappa_y$  the velocity of the fluid is bigger.

## 4. Conclusion

In this paper, a multi-relaxation time thermal lattice Boltzmann scheme has been applied to compute natural convection flow within differential heated square cavity. For Rayleigh number under  $10^6$  the present results compare favorably with previous benchmark solutions. Then anisotropic thermal diffusion is investigated ( $\kappa_x = \frac{\kappa_y}{2}$  and  $\kappa_x = 2\kappa_y$ ). The solution is compared to the isotropic case. We note the ability of double D2Q9 population to resolve anisotropic problem. Finally we remark when the  $x$  thermal diffusivity  $\kappa_x$  increase the velocity of the fluid increase and the convergence of the scheme to the steady state is faster.

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